

$$\dot{x} = Ax$$

THERE IS A  $P$  SUCH THAT  $PAP^{-1} = J$  IS IN JCF.

Let  $\bar{x} = Px$ . Then  $\dot{\bar{x}} = J\bar{x}$

$$\downarrow \|\bar{x}\| \leq \|P\| \|x\| \quad \downarrow \|x\| \leq \|P^{-1}\| \|\bar{x}\|$$

So  $\bar{x}$  IS BOUNDED OR  $\rightarrow 0$  IF AND ONLY IF  $x$  DOES.

SO FOR EACH JORDAN BLOCK,  $J_k$ ,

$$\dot{x}_k = J_k x_k$$

$$\Rightarrow x_k(t) = e^{J_k t} x_k(0)$$

$$= \underbrace{\begin{pmatrix} e^{\lambda_k t} & t e^{\lambda_k t} & & \\ & \ddots & \ddots & \\ & & 0 & t e^{\lambda_k t} \\ & & & \ddots & e^{\lambda_k t} \end{pmatrix}}_{m_k} x_k(0)$$

So IF  $\operatorname{Re}(\lambda_k) < 0$ ,  $\|x_k(t)\| \rightarrow 0$ .

IF  $\operatorname{Re}(\lambda_k) > 0$ ,  $\|x_k(t)\| \rightarrow \infty$

IF  $\operatorname{Re}(\lambda_k) = 0$ , THEN

$$\|x_k(t)\| = \|x_k(0)\| \quad \text{IF } m_k = 1$$

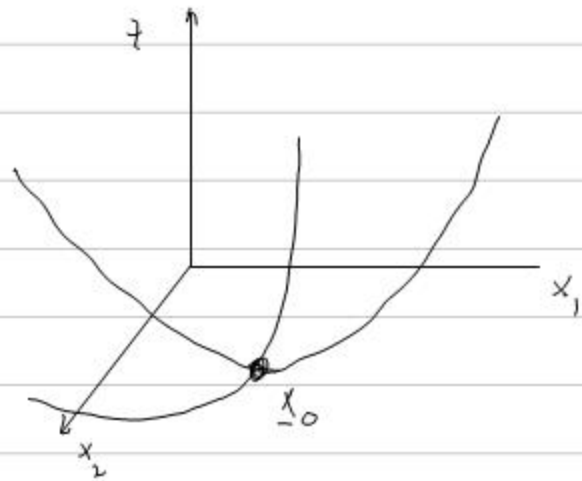
$$\downarrow \|x_k(t)\| \rightarrow \infty \quad \text{IF } m_k > 1$$

$$z = g(x)$$

$$\text{WITH } g(x_0) = 0$$

$$\downarrow g(x) > 0 \text{ FOR } x \neq x_0$$

$$\dot{x} = f(x)$$



IF WE KNOW THAT  $\dot{x}$  ALWAYS POINTS DOWNHILL ON THE SURFACE  $z = g(x)$ , THEN THE SYSTEM IS STABLE.

$$\text{SO WE NEED } \nabla g(x) \cdot \dot{x} < 0 \text{ FOR ALL } x$$

$$\Leftrightarrow \nabla g(x) \cdot f(x) < 0 \quad \text{" " } x$$

LINEAR CASE:  $z = x^T M x$  WITH  $M$  POSITIVE DEFINITE.

$$\begin{aligned} \text{FIND: } \nabla z(x) \cdot \dot{x} &= \nabla z(x) \cdot A x \\ &= 2 x^T M \cdot A x \\ &= x^T (2 M A) x \\ &= x^T (M A + A^T M^T) x \\ &= x^T (A^T M + M A) x \end{aligned}$$

SO IF  $\nabla z(x) \cdot \dot{x} < 0$  FOR  $x \neq 0$ , THEN

$$A^T M + M A = -N \quad \text{WITH } N \text{ POS. DEF.}$$

$$\begin{aligned}
 A^T M + M A &= \int_0^{\infty} (A^T e^{A^T t} N e^{A t} + e^{A^T t} N e^{A t} A) dt \\
 &= \int_0^{\infty} \frac{d}{dt} (e^{A^T t} N e^{A t}) dt \\
 &= 0 - e^{A^T 0} N e^{A 0} \\
 &= -N
 \end{aligned}$$

$$= \int_0^{\infty} e^{A^T t} N e^{A t} dt$$

$$\begin{aligned}
 x^T \int_0^{\infty} e^{A^T t} N_0^T N_0 e^{A t} dt x &= \int_0^{\infty} x^T e^{A^T t} N_0^T N_0 e^{A t} x dt \\
 &= \int_0^{\infty} (N_0 e^{A t} x)^T (N_0 e^{A t} x) dt \\
 &= \int_0^{\infty} \underline{y}^T \underline{y} dt = \int_0^{\infty} \|\underline{y}\|^2 dt
 \end{aligned}$$

WHERE  $\underline{y} = N_0 e^{A t} x$

Ex. 5.5  $\dot{\underline{x}} = \begin{pmatrix} -1 & e^{2t} \\ 0 & -1 \end{pmatrix} \underline{x} = A(t) \underline{x}$

EIGENVALUES OF  $A(t)$ :  $\lambda = -1$ , MULT. 2.

BUT THE SOLUTION:

$$\dot{x}_1 = -x_1 + e^{2t} x_2$$

$$+ \dot{x}_2 = -x_2 \implies x_2(t) = e^{-t} x_2(0)$$

$$+ \dot{x}_1 = -x_1(t) + e^t x_2(0)$$

$$\implies x_1(t) = A e^{-t} + B e^t \text{ — UNBOUNDED.}$$

So system is UNSTABLE.

$$\underline{u}(t) = -B^T e^{A^T(t_1-t)} W_c^{-1}(t_1) [e^{A^T t_1} x_0 - x_1] e^{A^T t}$$

$$\underline{x}(t) = e^{At} x_0 + \int_0^t e^{A(t-z)} B u(z) dz$$

$$\Rightarrow \underline{x}(t) = e^{At} x_0 - \int_0^t e^{A(t-z)} B B^T e^{A^T(t_1-z)} W_c^{-1}(t_1) (e^{A^T t_1} x_0 - x_1) dz$$

$$= e^{At} x_0 - \int_0^t e^{A(t-z)} B B^T e^{A^T(t_1-z)} dz W_c^{-1}(t_1) (e^{A^T t_1} x_0 - x_1)$$

$$\Rightarrow \underline{x}(t_1) = e^{A t_1} x_0 - W_c(t_1) W_c^{-1}(t_1) (e^{A^T t_1} x_0 - x_1) \\ = x_1$$

$$x' e^{At} B = 0 \quad \text{FOR ALL } t \in [0, t_1] \text{ WITH } t_1 > 0$$

$$\Leftrightarrow x' A^k B = 0 \quad \text{FOR ALL } k, 0 \leq k \leq n-1$$

$$\text{OR } x' \left( \sum_{l=0}^{\infty} \frac{A^l}{l!} t^l \right) B = 0$$

$$\Leftrightarrow \sum_{l=0}^{\infty} x' A^l B \cdot \frac{t^l}{l!} = 0 \quad \text{FOR ALL } t \in [0, t_1]$$

$$\Leftrightarrow x' A^l B = 0 \quad \text{FOR ALL } l \geq 0$$

$$\Leftrightarrow x' A^l B = 0 \quad \text{FOR ALL } l \text{ WITH } 0 \leq l \leq n-1$$

(BY COYLE-HAMILTON)