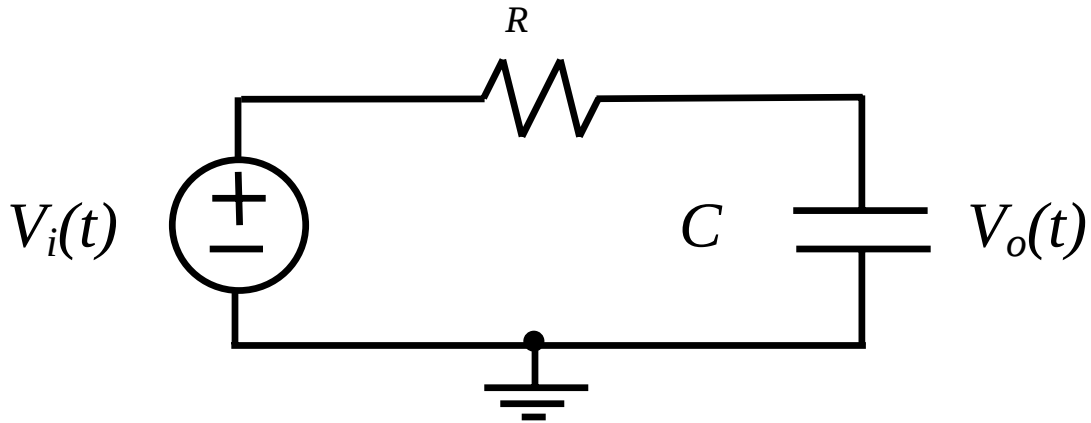


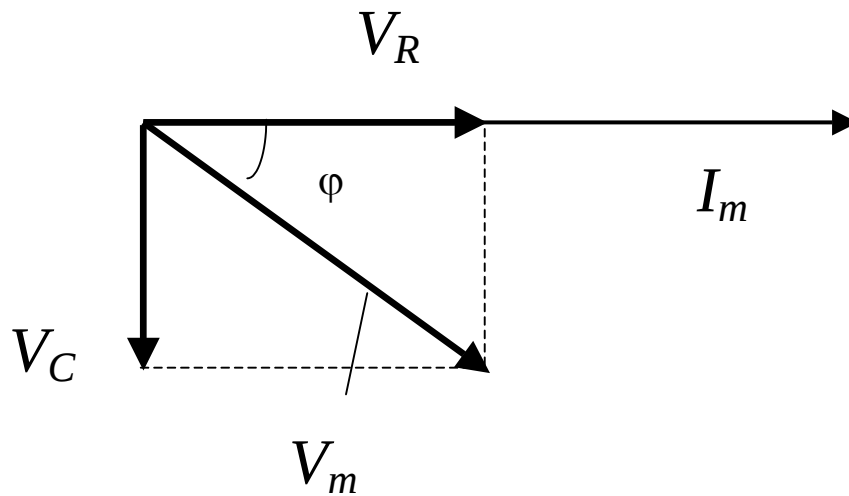
Phasor Diagram of an RC Circuit

$$V(t) = V_m \sin(\omega t)$$



- Current is a reference in *series* circuit

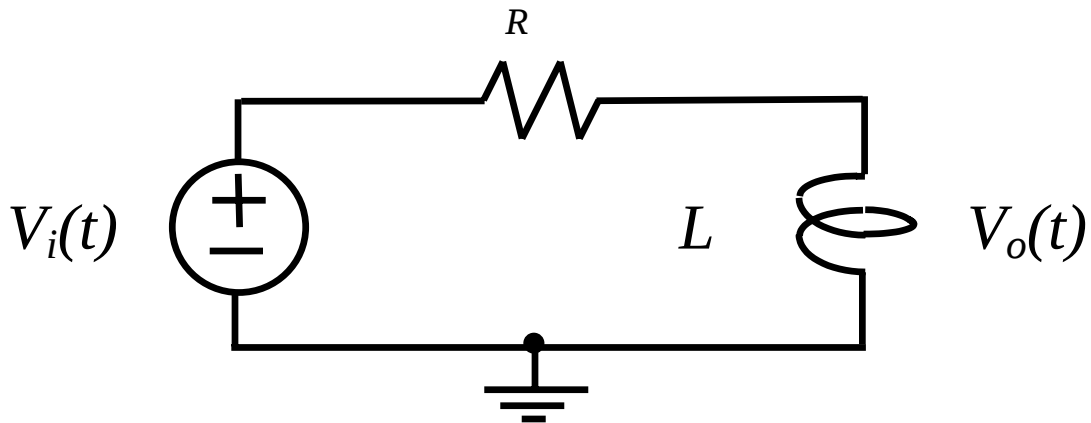
$$\text{KVL: } \overline{V_m} = \overline{V_R} + \overline{V_C}$$



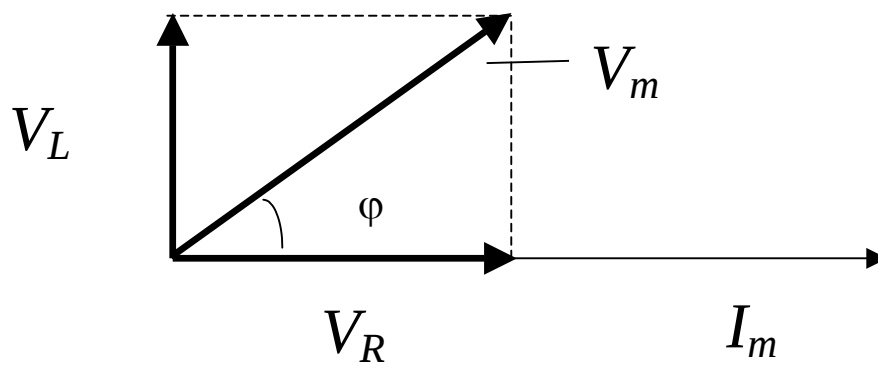
Phasor Diagram of an RL Circuit

$$V(t) = V_m \sin(\omega t)$$

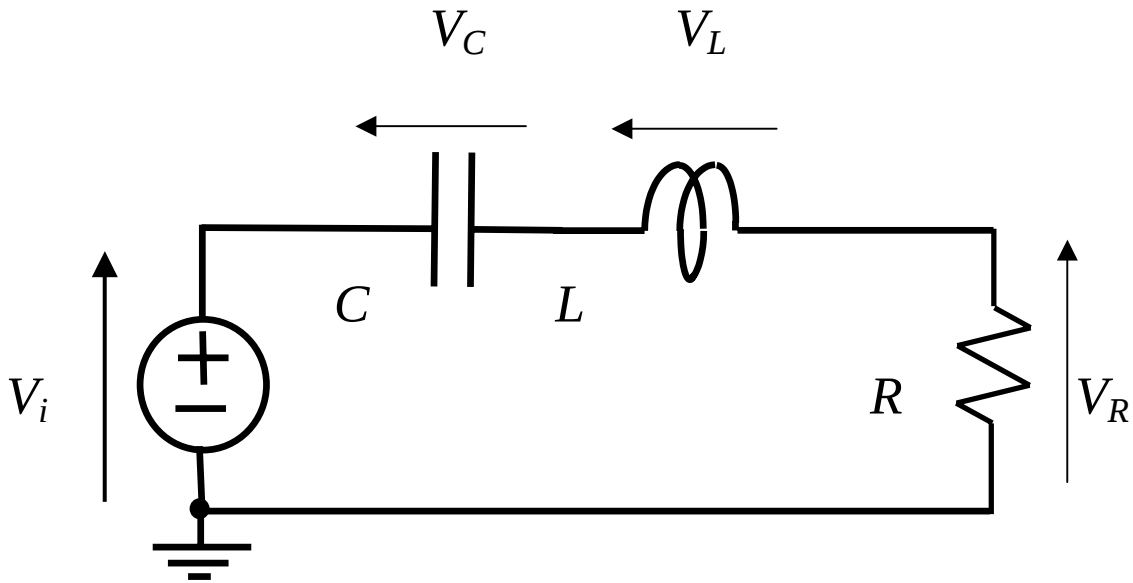
$$V_R(t)$$



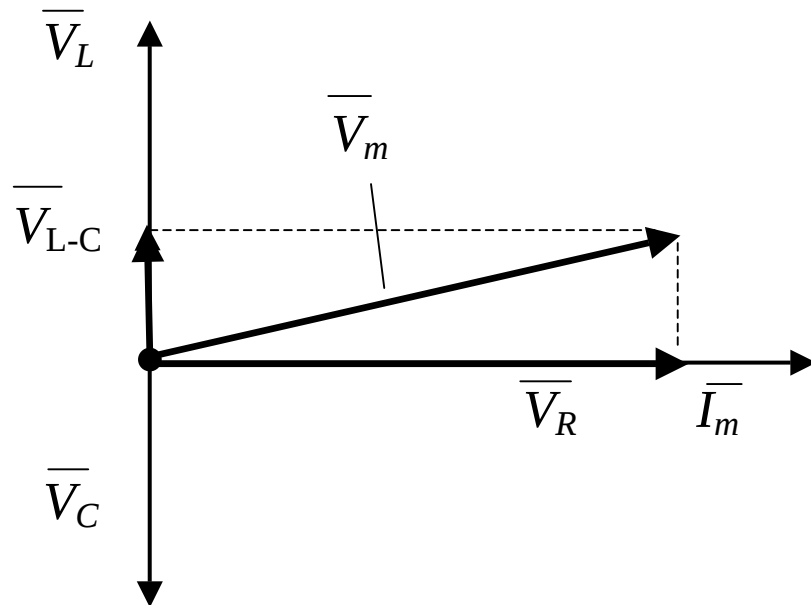
$$\text{KVL: } V_m = V_R + V_L$$



Phasor Diagram of a Series *RLC* Circuit

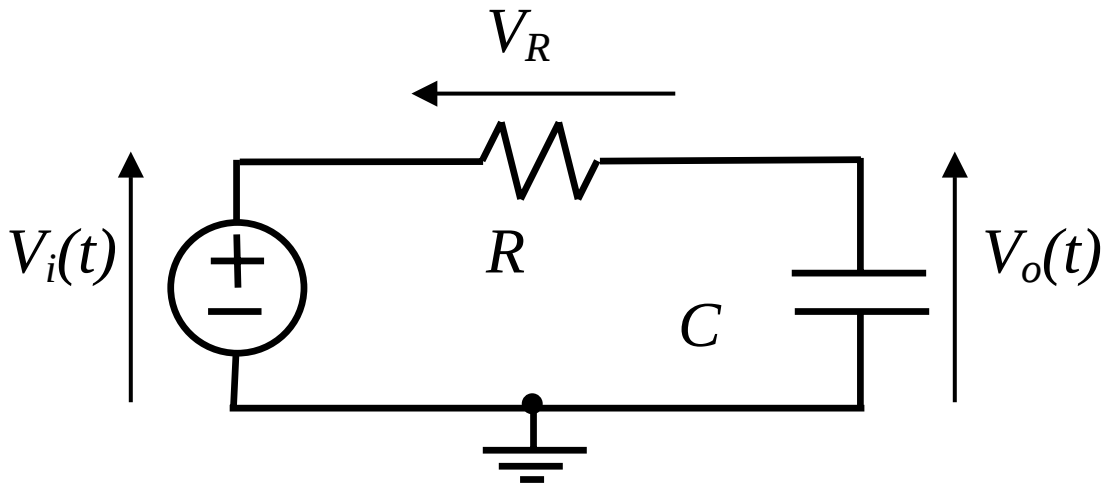


KVL: $\overline{V_m} = \overline{V_C} + \overline{V_L} + \overline{V_R}$



- Voltages across capacitor and inductor *compensate each other*

Integrating Circuit



$$\bar{V}_i = \bar{V}_R + \bar{V}_C \quad \text{or} \quad |V_i| = \sqrt{|V_R|^2 + |V_C|^2}$$

- Assume high frequency $1/\omega C \ll R$ then $V_R \gg V_C$

$V_R \approx V_i$

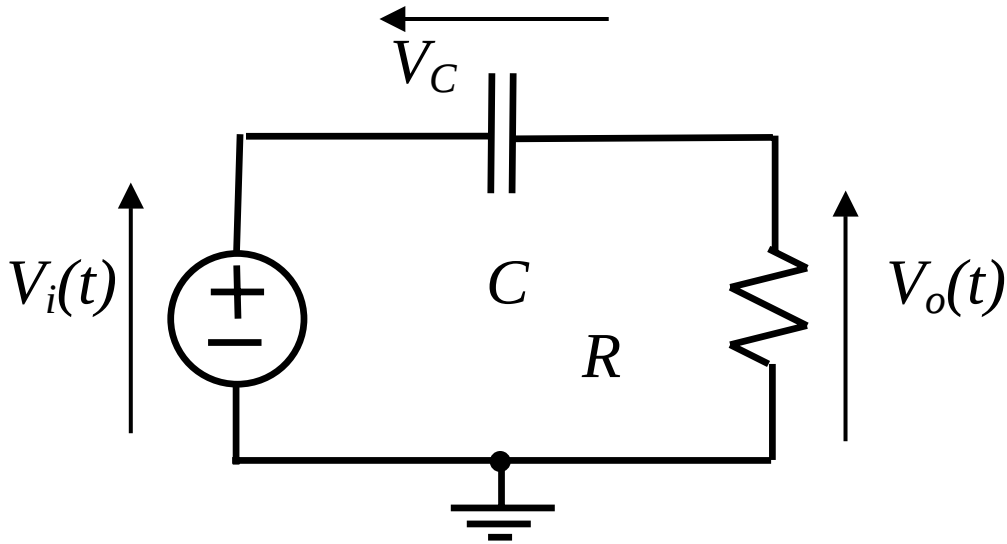
V_i

$$V_o = \frac{1}{C} \int_0^t I_i dt \approx \frac{1}{RC} \int_0^t V_i dt$$

$$V_o \propto \int V_i dt$$

- Accurate integrating can be obtained at *high frequency* that leads to a *low* output signal

Differentiating Circuit



$$\bar{V}_i = \bar{V}_R + \bar{V}_C \quad \text{or} \quad |V_i| = \sqrt{|V_R|^2 + |V_C|^2}$$

- Assume low frequency $1/\omega C \gg R$ then $V_R \ll V_C$

$$V_C \approx V_i$$

$$V_i \approx \frac{1}{C} \int_0^t I_i dt \Rightarrow I_i = C \frac{d}{dt} V_i$$

$$V_O = V_R = I_i R \approx RC \frac{d}{dt} V_i$$

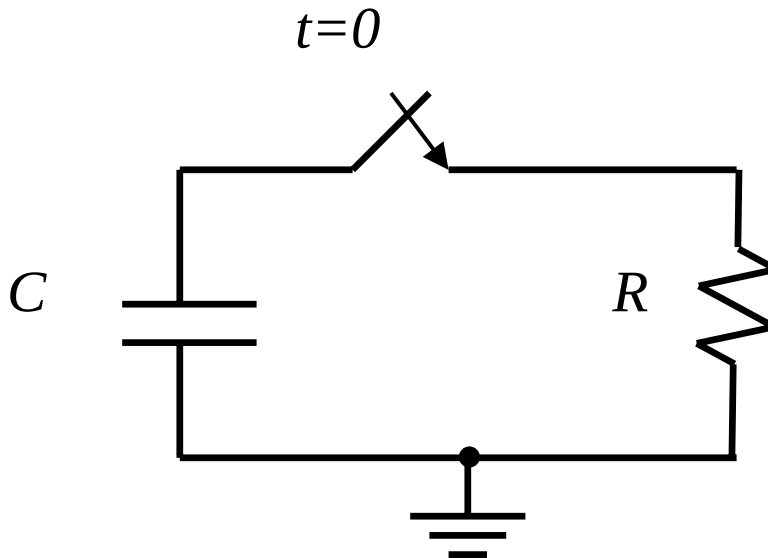
$$V_O \propto \frac{d}{dt} V_i$$

- An accurate result can be achieved at low frequency.

Transient Processes in Passive Circuits

RC Circuit without a Source

- The circuit response is due only to the energy *stored* in the capacitor



- The capacitor C is precharged to the voltage V_0
Applying KCL:

$$C \, dV/dt + V/R = 0$$

- This is the 1st order differential equation

Solution of the Differential Equation

$$dV/dt + V/RC = 0$$

$$dV/V = -dt/RC$$

$$\ln V = -t/RC + a$$

$$V = A e^{-t/RC}, \quad A = e^{+a}$$

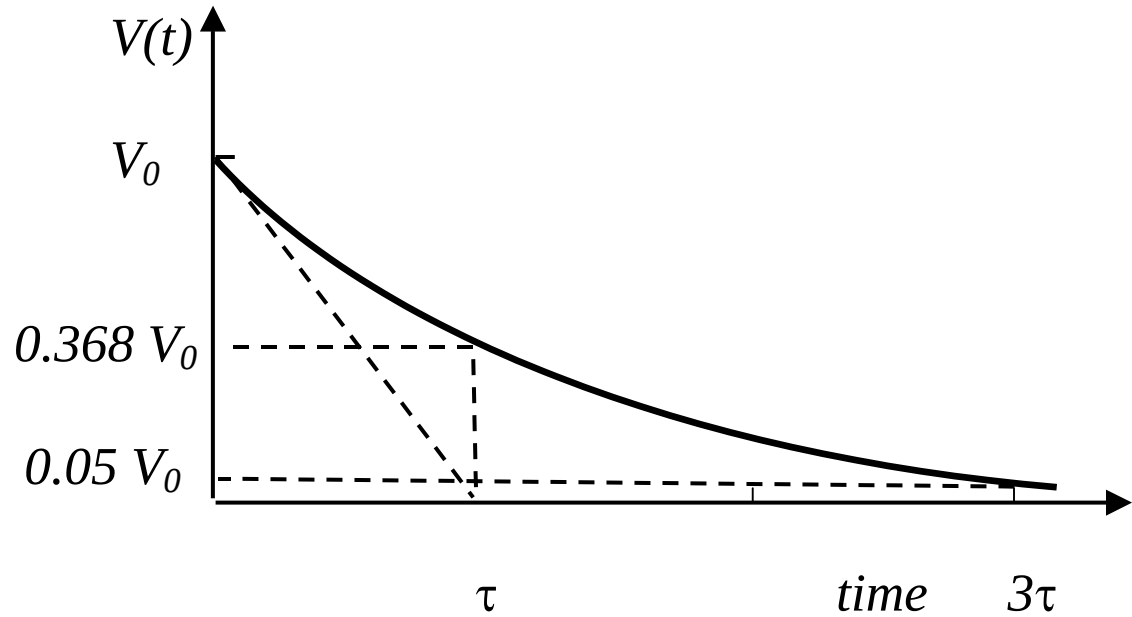
- e is the base of the natural logarithms, $e = 2.718...$
- *Continuity* requires the initial condition:

$$\text{At } t = 0 \quad V(0) = V_0$$

$$V(t) = V_0 e^{-t/RC}$$

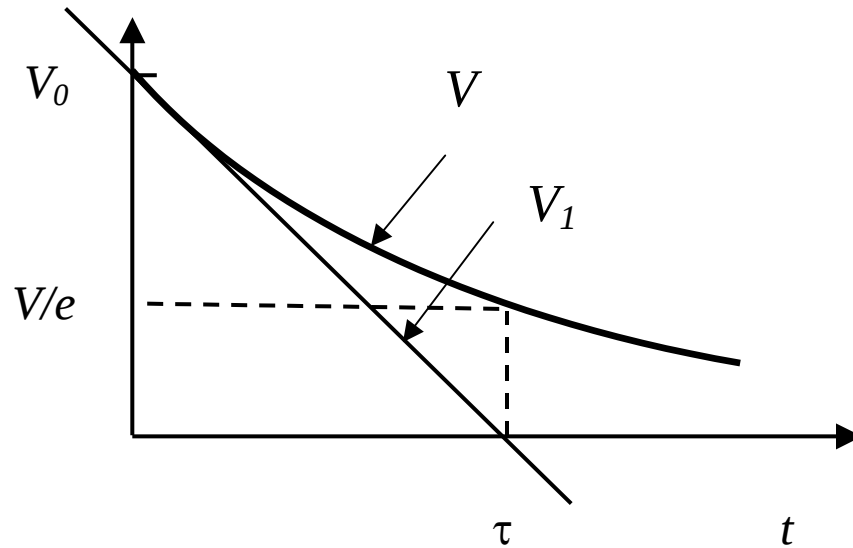
- The response governed by the elements themselves without external force is called a *natural response*

The Time Constant



- The *time constant* $\tau = RC$ is the rate at which the natural response decays to zero
- Time τ is required to decay by a factor of $1/e=0.368$
- After the time period of 3τ the transient process is considered to be completed

Determination of the Time Constant



1) From the solution of the equation

By definition: as the time when the signal decreases by $1/e$

$$V(t+\tau)/V(t) = 1/e$$

The time t can be chosen arbitrarily

2) From the slope of the line at $t=0$

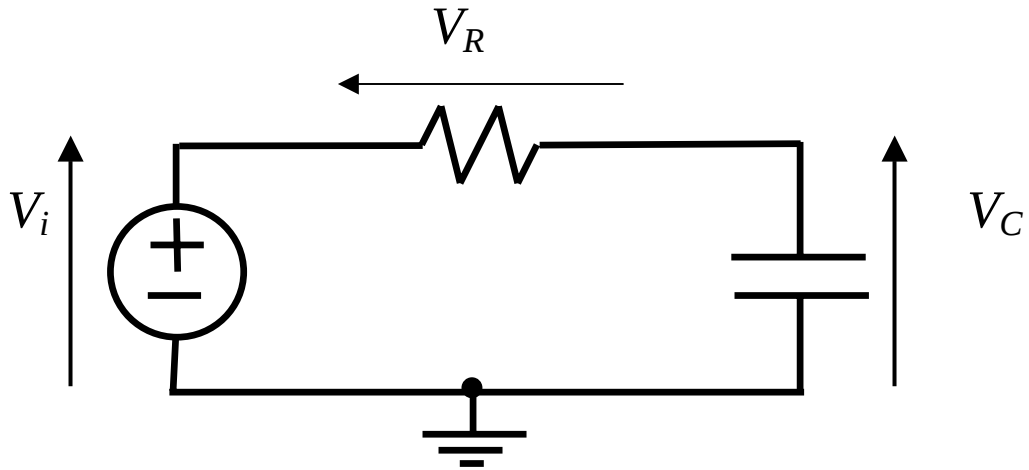
Differentiating the solution

$$dV/dt = -\{V_0/\tau\} e^{-t/\tau}$$

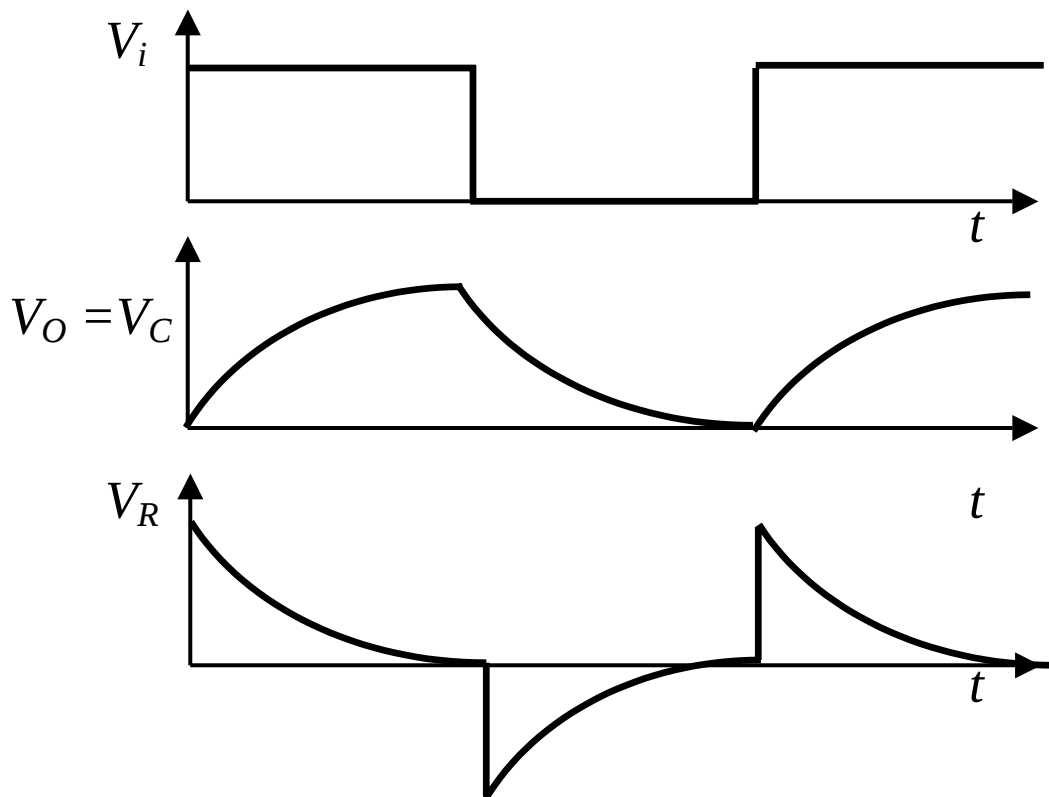
$$V_1(t) = -\{V_0/\tau\} t + V_0$$

$$V_1(\tau) = 0$$

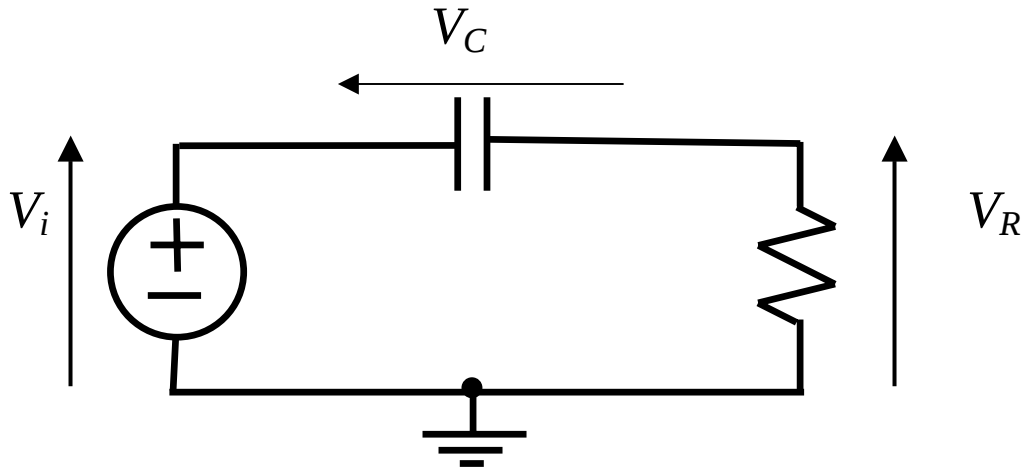
Transient Response of an *Integrating RC* Circuits



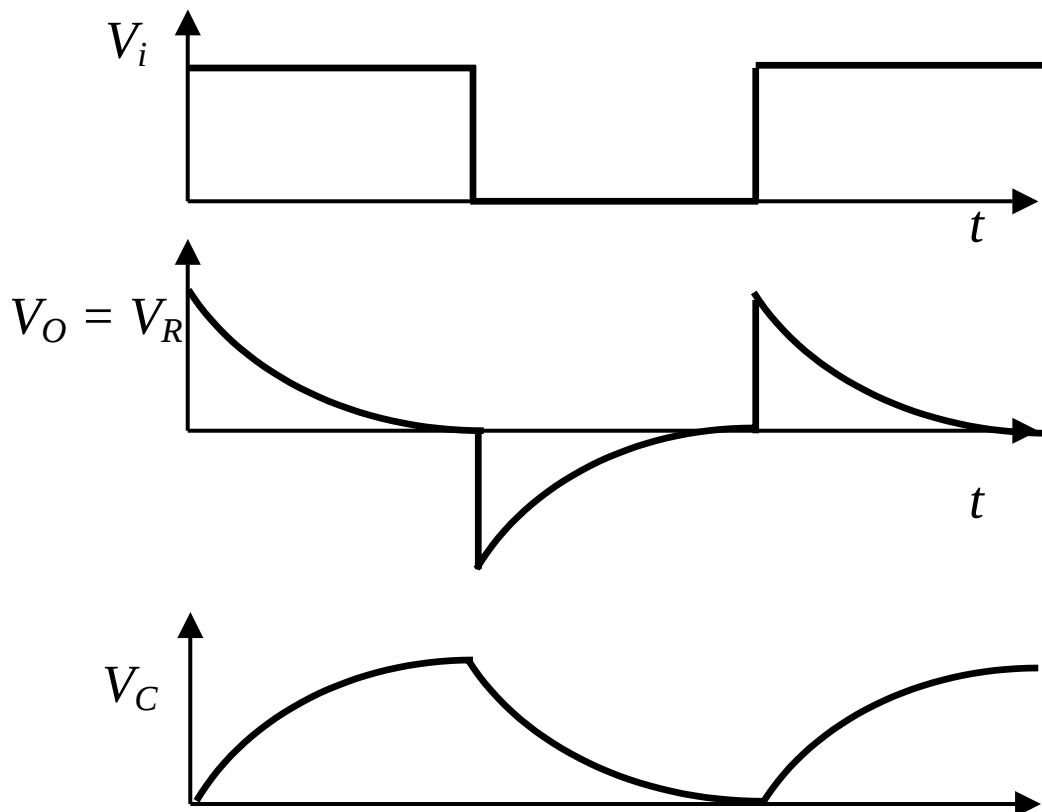
$$\text{KVL: } \overline{V_i} = \overline{V_R} + \overline{V_C}$$



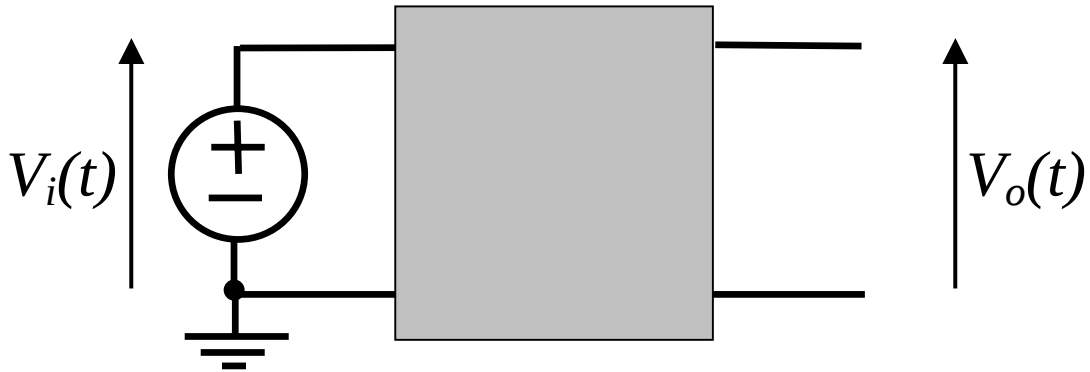
Transient Response of a *Differentiating* RC Circuits



$$\text{KVL: } \overline{V_i} = \overline{V_C} + \overline{V_R}$$



Transfer Function



$$V_i(t) = V_{im} \cos(\omega t) \quad V_o(t) = V_{om} \cos(\omega t + \phi)$$

$\downarrow$
 $V_{om}(\omega)$

$\downarrow$
 $\phi(\omega)$

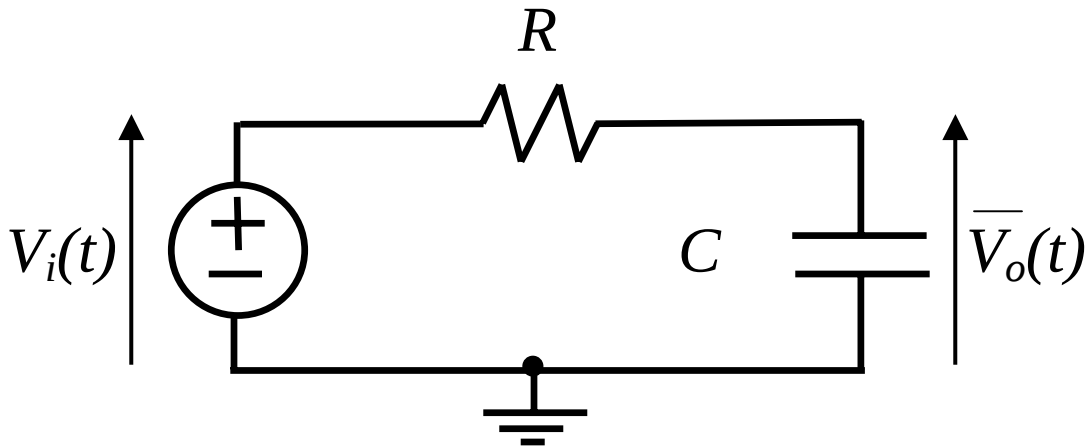
$$V_o(t) = \text{Re} \{ \overline{V_o} e^{j\omega t} \}, \quad \overline{V_o} = V_{om} e^{j\phi}$$

$$T(\omega) = \frac{\overline{V_o}(\omega)}{V_i}$$

Amplitude response $|T(\omega)| = V_{om}(\omega)/V_{im}$

Phase response $\angle T(\omega) = \phi(\omega)$

The Transfer Function of an *Integrating RC* Circuit



$$\bar{T}(\omega) = \frac{\bar{V}_o(\omega)}{V_i} = \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC}$$

$$\bar{T}(\omega) = \frac{1}{1 + j\omega\tau}$$

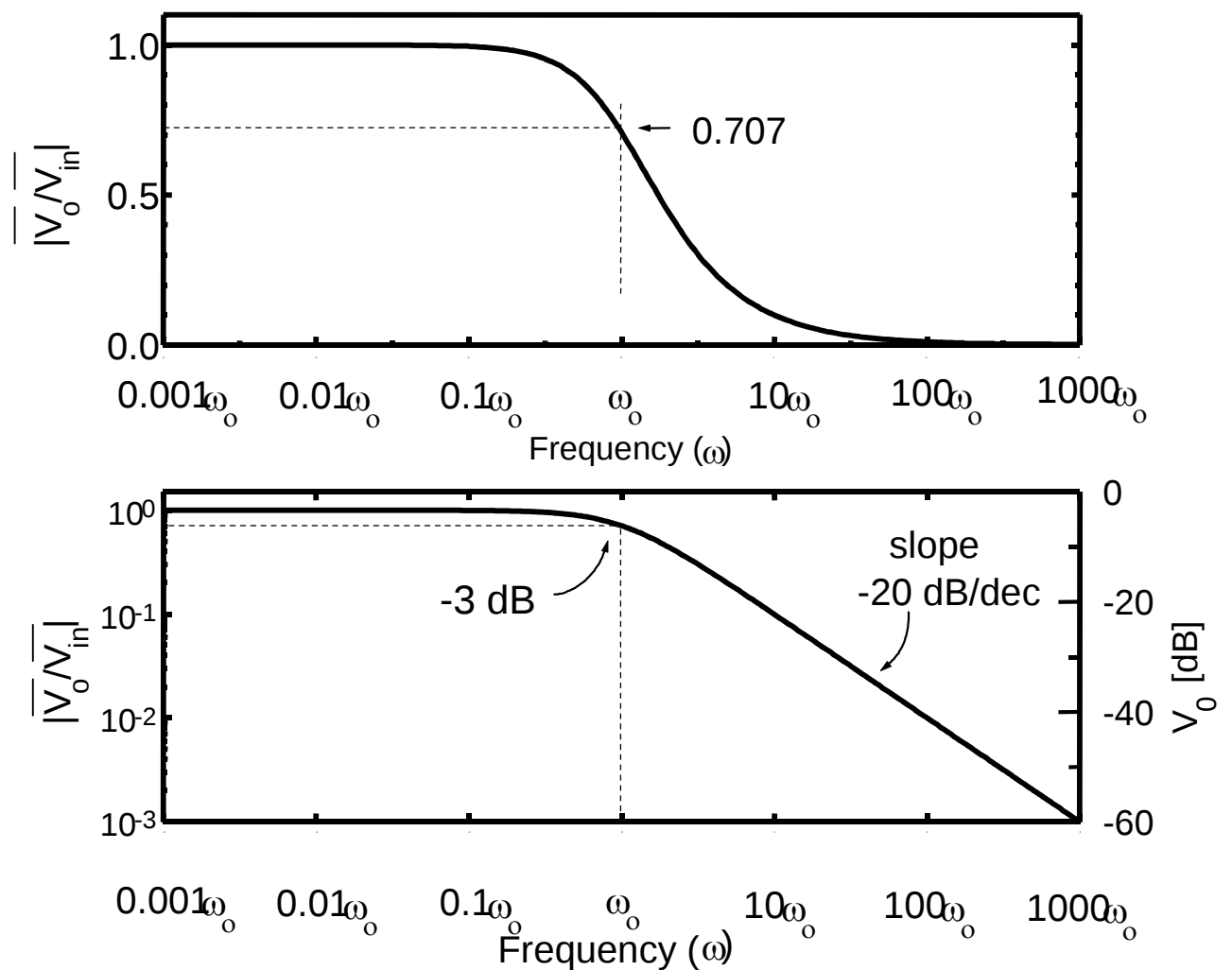
$$\tau = RC$$

Amplitude Response of the Integrating RC Circuit

- The *magnitude* of the transfer function is

$$\left| \overline{T}(\omega) \right| = \frac{1}{\sqrt{1 + \omega^2 \tau^2}}$$

- The Integrating RC circuit is a LOW-PASS filter

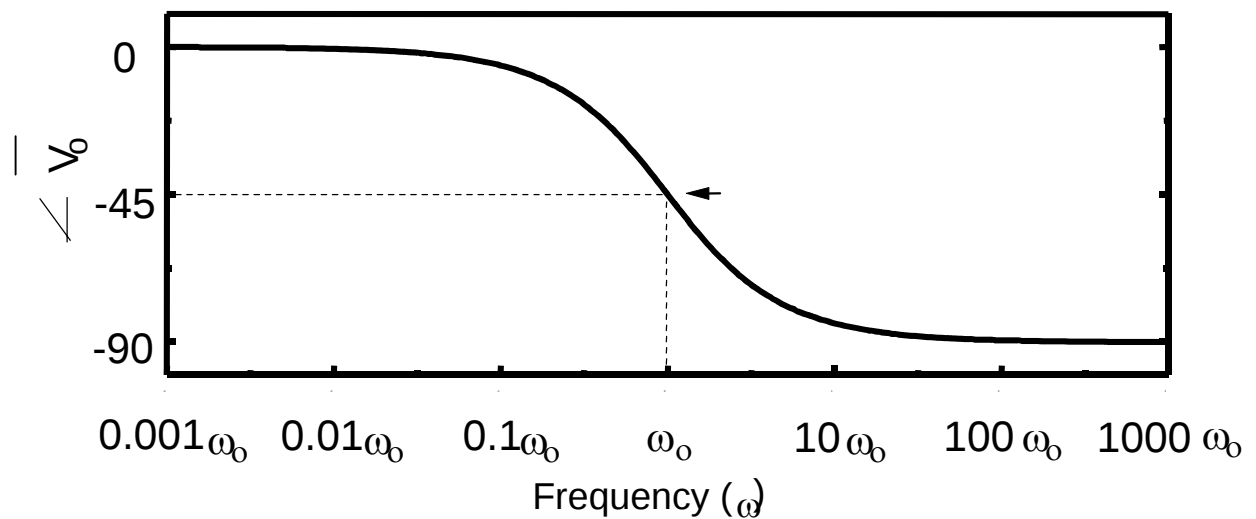


Phase Response of the Integrating RC Circuit

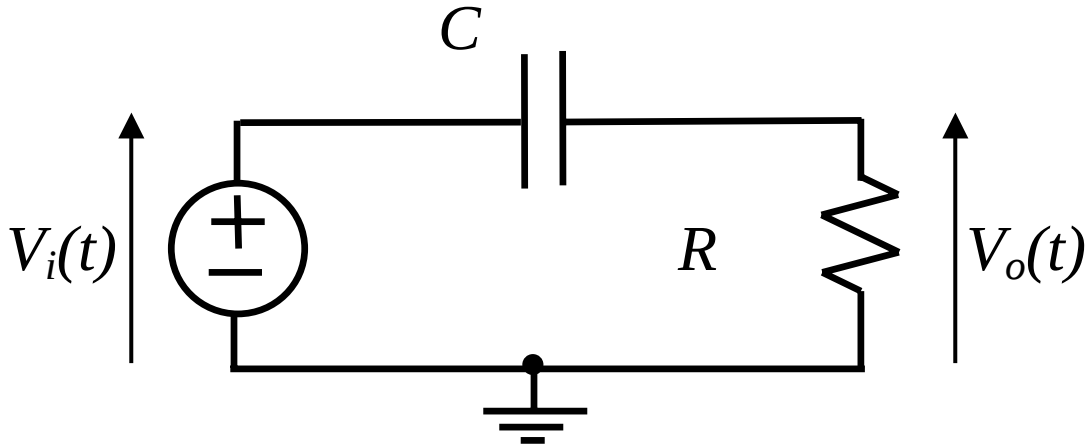
The *angle* of the transfer function is

$$\angle \bar{T}(\omega) = \arctan \frac{\text{Im}[T(\omega)]}{\text{Re}[T(\omega)]}$$

$$\angle \bar{T}(\omega) = \angle \frac{1 - j\omega\tau}{(1 + j\omega\tau)(1 - j\omega\tau)} = -\arctan(\omega\tau)$$



The Transfer Function of a *Differentiating* RC Circuit



$$\bar{T}(\omega) = \frac{\overline{V_o}(\omega)}{V_i} = \frac{\overline{I}(\omega) \cdot R}{\overline{I}(\omega) \cdot X_{RC}(\omega)}$$

$$\bar{T}(\omega) = \frac{R}{X_{RC}(\omega)} = \frac{R}{R + \frac{1}{j\omega C}} = \frac{j\omega RC}{1 + j\omega RC}$$

$$\bar{T}(\omega) = \frac{j\omega\tau(1 - j\omega\tau)}{1 + \omega^2\tau^2} = \frac{\omega\tau(\omega\tau + j)}{1 + \omega^2\tau^2}$$

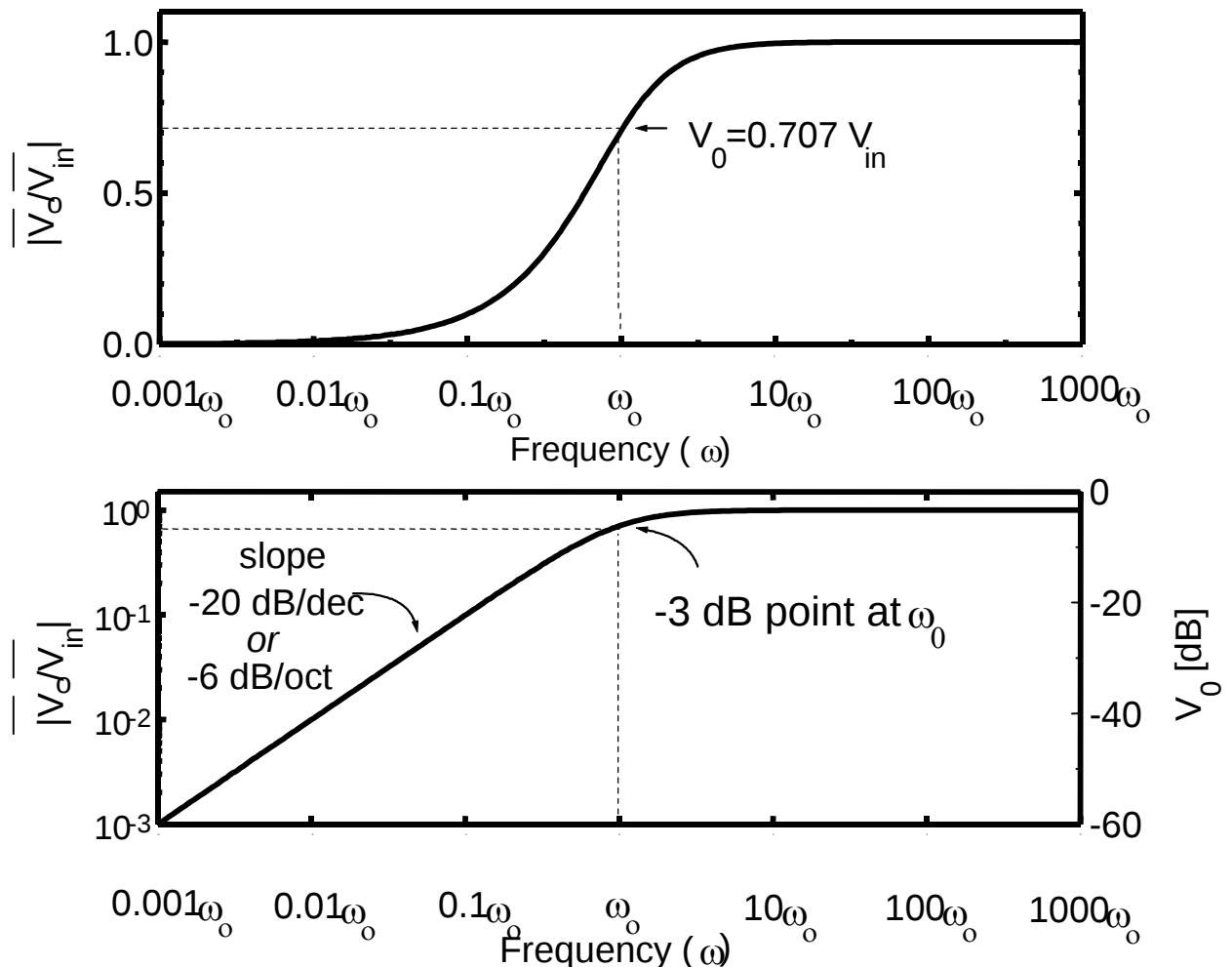
$$\tau = RC$$

Amplitude response of the Differentiating RC Circuit

- Amplitude response of the RC circuit is the magnitude of $\overline{T}(\omega)$

$$\left| \overline{T}(\omega) \right| = \left| \frac{\omega\tau(\omega\tau + j)}{1 + \omega^2\tau^2} \right| = \frac{\omega\tau}{\sqrt{1 + \omega^2\tau^2}}$$

- The Differentiating RC circuit is a *HIGH-PASS* filter

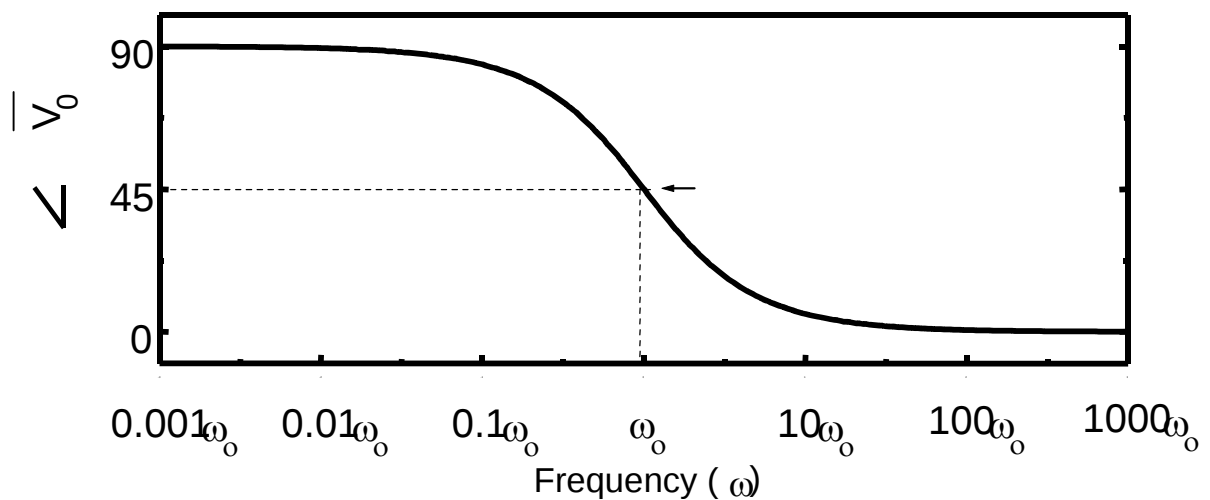


Phase response of the Differentiating RC Circuit

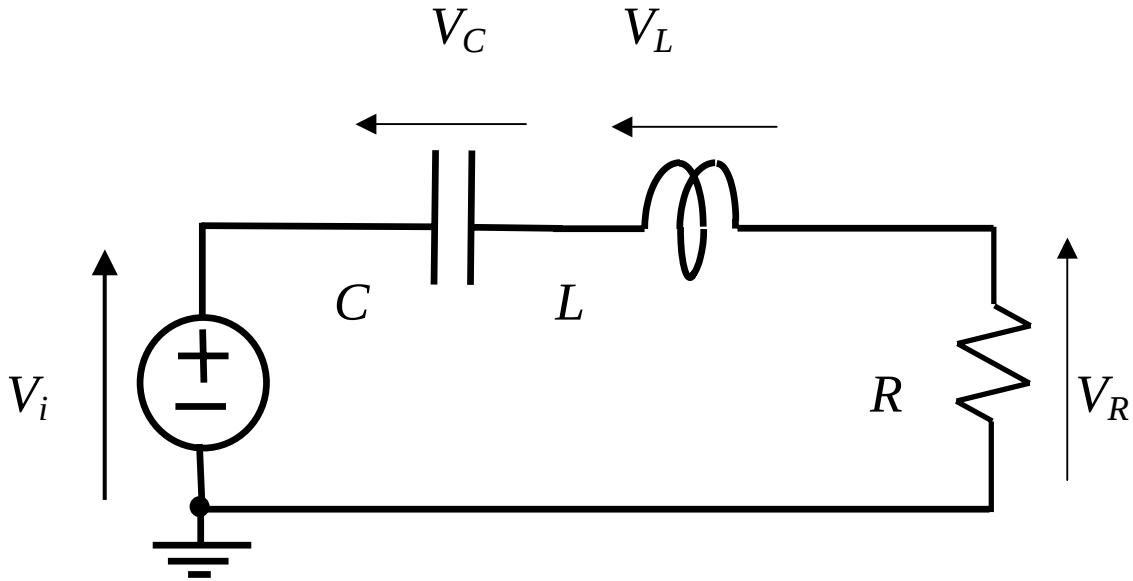
- *Phase response of the RC circuit is the phase angle of $\bar{T}(\omega)$*

$$\angle \bar{T}(\omega) = \angle \left\{ \frac{\omega\tau(\omega\tau + j)}{1 + \omega^2\tau^2} \right\}$$

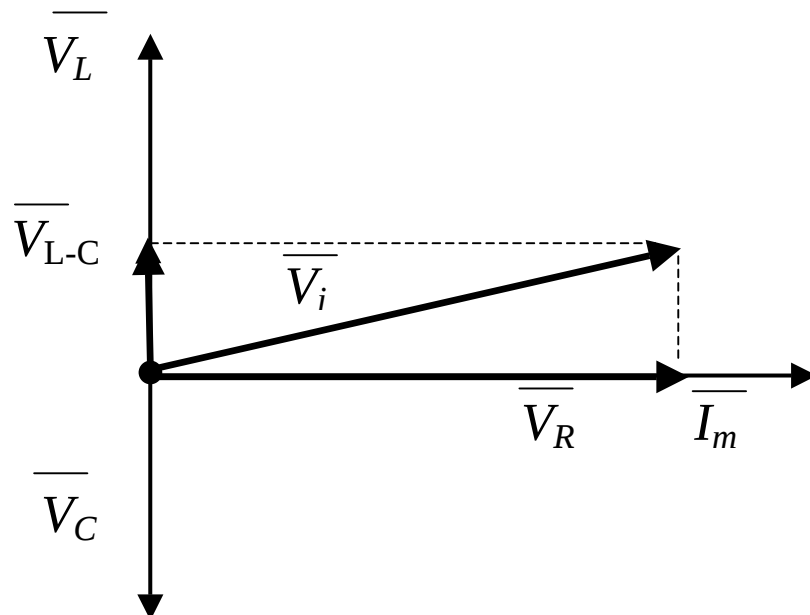
$$\angle \bar{T}(\omega) = \arctan \frac{1}{\omega\tau}$$



Frequency Response of a Series *RLC* Circuit



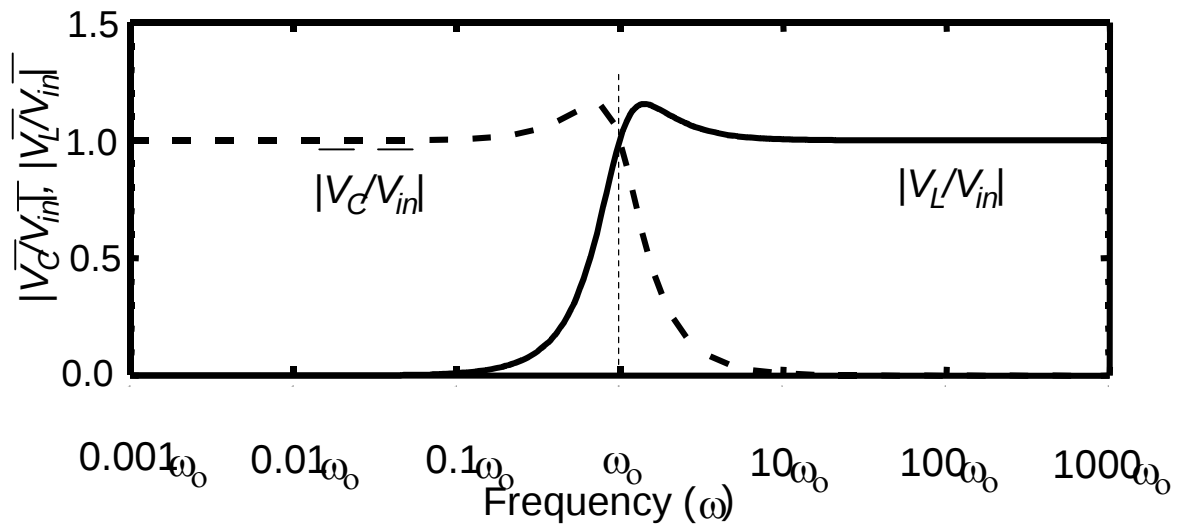
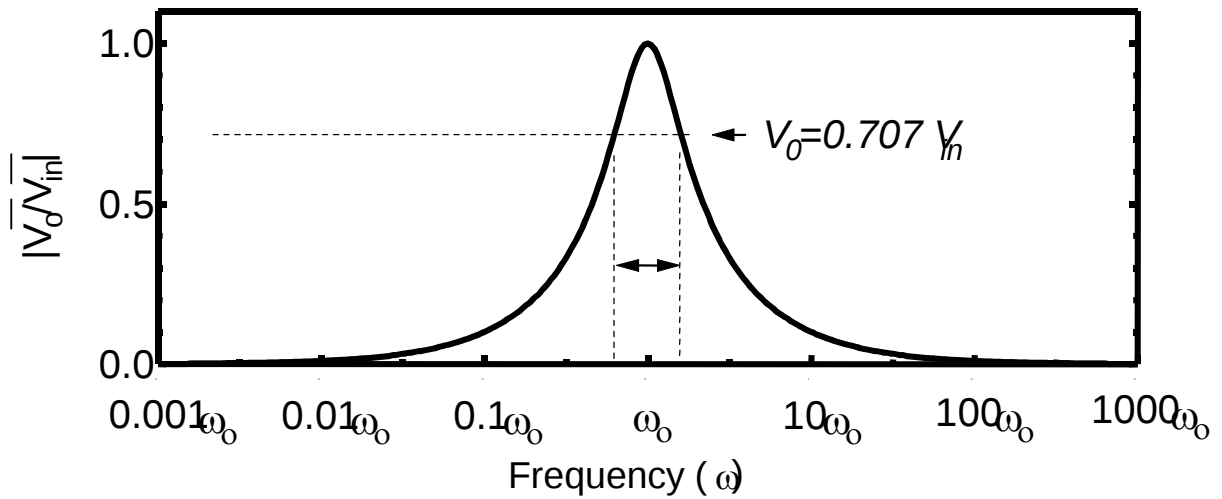
$$\text{KVL: } \overline{V_i} = \overline{V_C} + \overline{V_L} + \overline{V_R}$$



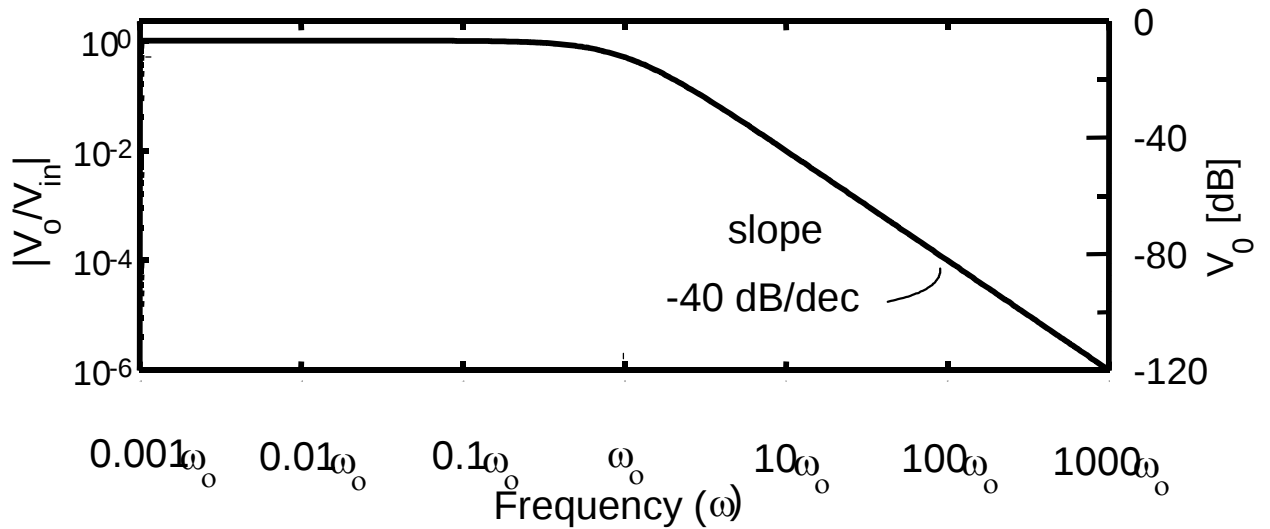
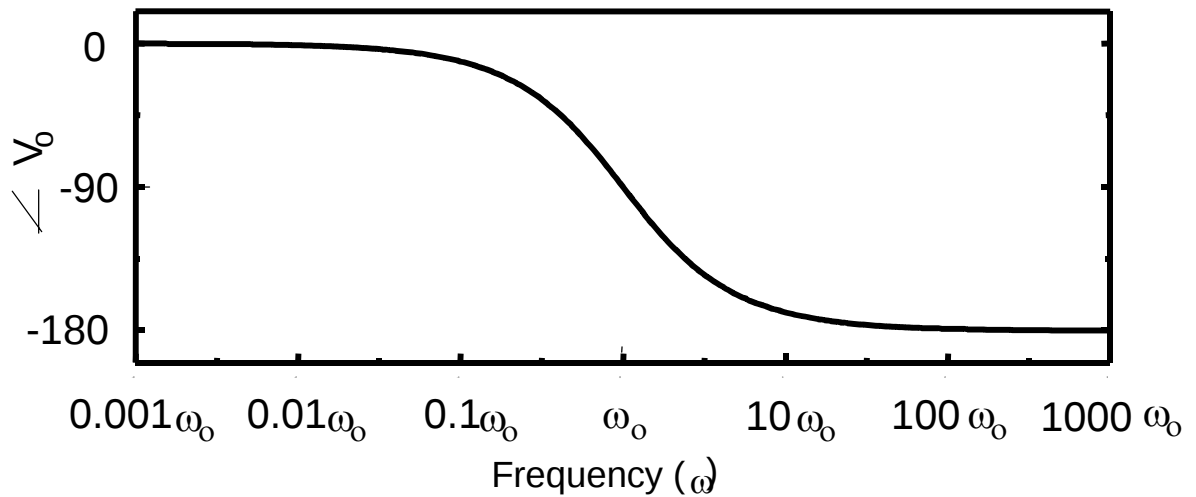
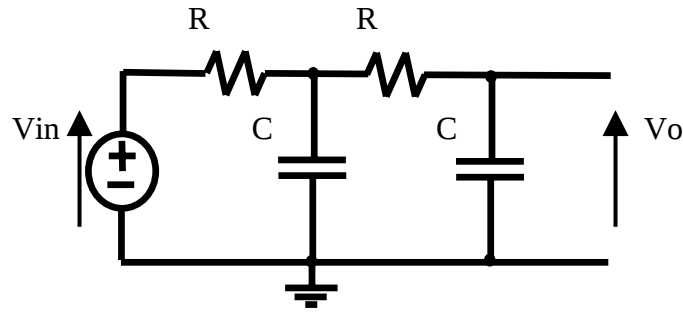
- Voltages across capacitor and inductor *compensate each other*

Amplitude Response of a Series *RLC* Circuit

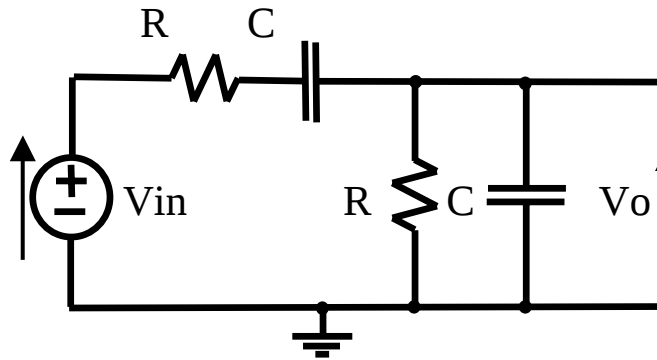
$$|\bar{V}_0 / \bar{V}_{IN}| = \frac{R}{\left| j\omega L + \frac{1}{j\omega C} + R \right|} = \frac{R}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2}}$$



Amplitude and Phase Response of the Ladder RC Circuit



Amplitude and Phase Response of a Wien-Bridge Circuit



$$\bar{T}(\omega) = \frac{Z_{OUT}}{Z_{TOTAL}} = \frac{\left(\frac{1}{R} + j\omega C\right)^{-1}}{\left(\frac{1}{R} + j\omega C\right)^{-1} + R + \frac{1}{j\omega C}}$$

