

ESE 503 - Stochastic Systems

Fall 1999

Solutions to Homework # 6

Problem 6.50:

$$\begin{aligned}X(t, \omega) &= \omega \cos(2\pi t) \\m_X(t) &= E[\omega] \cos(2\pi t) = 0 \\C_X(t_1, t_2) &= \text{Var}[\omega] \cos(2\pi t_1) \cos(2\pi t_2) \\&= \frac{1}{3} \cos(2\pi t_1) \cos(2\pi t_2)\end{aligned}$$

Since $C_X(t_1, t_2)$ does not depend only on $t_1 - t_2$, the process is not WSS. Hence, it is also not SSS.

Problem 6.51: $X(t) = \cos(\omega t + \Theta)$. From Example 6.7, $m_X(t) = 0$ and $C_X(t_1, t_2) = (1/2) \cos[\omega(t_1 - t_2)]$. Thus, $X(t)$ is WSS. It can also be checked from the n -th order joint pdf that $X(t)$ is SSS.

Problem 6.53: $X(t) = A \cos(\omega t) + B \sin(\omega t)$.

(a)

$$\begin{aligned}E[X(t)] &= E[A \cos(\omega t) + B \sin(\omega t)] \\&= E[A] \cos(\omega t) + E[B] \sin(\omega t) \\&= 0 \\C_X(t_1, t_2) &= E[(A \cos(\omega t_1) + B \sin(\omega t_1))(A \cos(\omega t_2) + B \sin(\omega t_2))] \\&= E[A^2] \cos(\omega t_1) \cos(\omega t_2) + E[B^2] \sin(\omega t_1) \sin(\omega t_2) \\&\quad + \underbrace{E[A]E[B]}_{=0} \cos(\omega t_1) \sin(\omega t_2) + \underbrace{E[A]E[B]}_{=0} \sin(\omega t_1) \cos(\omega t_2) \\&= E[A^2] \cos(\omega t_1) \cos(\omega t_2) + E[B^2] \sin(\omega t_1) \sin(\omega t_2) \\&= E[A^2](\cos(\omega t_1) \cos(\omega t_2) + \sin(\omega t_1) \sin(\omega t_2)) \\&\quad (A \text{ and } B \text{ are iid, zero-mean r.v.}) \\&= E[A^2](1/2) \cos(\omega(t_1 - t_2))\end{aligned}$$

Thus $X(t)$ is WSS.

(b)

$$\begin{aligned}E[X^3(t)] &= E[(A \cos(\omega t) + B \sin(\omega t))^3] \\&= E[A^3] \cos^3(\omega t) + 3E[A^2]E[B] \cos^2(\omega t) \sin(\omega t) \\&\quad + 3E[A]E[B^2] \cos(\omega t) \sin^2(\omega t) + E[B^3] \sin^3(\omega t) \\&= E[A^3] \cos^3(\omega t) + E[B^3] \sin^3(\omega t)\end{aligned}$$

If $\omega \neq 0$, the third moment of $X(t)$ varies with time. Thus, $X(t)$ is not SSS.

Problem 6.55: $Z_n = (1/2)Z_{n-1} + X_n$, $Z_0 = 0$, where X_n is zero-mean iid.

(a) Solving the difference equation, we obtain

$$Z_n = \sum_{i=1}^n (1/2)^{n-i} X_i$$

Thus $E[Z_n] = 0$. Now assuming that $m \leq n$.

$$\begin{aligned} C_Z(m, n) &= E[Z_m Z_n] \\ &= E \left[\left(\sum_{i=1}^m (1/2)^{m-i} X_i \right) \left(\sum_{j=1}^n (1/2)^{n-j} X_j \right) \right] \\ &= \sum_{i=1}^m \sum_{j=1}^n (1/2)^{m+n-i-j} E[X_i X_j] \\ &= \sum_{i=1}^m (1/2)^{m+n-2i} E[X_i^2] \\ &= E[X_1^2] \sum_{i=1}^m (1/2)^{m+n-2i}. \end{aligned}$$

Since

$$E[X_i X_j] = \begin{cases} 0 & \text{if } i \neq j \\ E[X_i^2] & \text{if } i = j \end{cases}.$$

From the above, we see that $C_Z(m, n)$ depends on both m and n . Thus the process is not WSS.

(b) From the above, we see that

$$\begin{aligned} C_Z(m, m+k) &= E[X_1^2] \sum_{i=1}^m (1/2)^{2m+k-2i} \\ &= E[X_1^2] (1/4)^m (1/2)^k \sum_{i=1}^m (4)^i \\ &= E[X_1^2] (1/4)^m (1/2)^k \left(\frac{4 - 4^{m+1}}{1 - 4} \right) \\ &= E[X_1^2] (1/2)^k \left(\frac{4 - (1/4)^{m-1}}{3} \right) \\ &= \frac{4}{3} E[X_1^2] (1/2)^k \quad \text{as } m \rightarrow \infty \end{aligned}$$

Thus, Z_n is asymptotically WSS.

(c) From the above, the pdf of Z_n approaches $\mathcal{N}(0, 4/3)$

Problem 6.57: $Z(t) = aX(t) + bY(t)$, where $X(t)$ and $Y(t)$ are independent, zero-mean WSS processes with the same covariance function $C_X(\tau)$.

(a)

$$\begin{aligned} E[Z(t)] &= E[aX(t) + bY(t)] \\ &= aE[X(t)] + bE[Y(t)] \\ &= 0 \\ C_Z(t_1, t_2) &= E[(aX(t_1) + bY(t_1))(aX(t_2) + bY(t_2))] \\ &= a^2E[X(t_1)X(t_2)] + b^2E[Y(t_1)Y(t_2)] \\ &\quad + abE[X(t_1)Y(t_2)] + abE[Y(t_1)X(t_2)] \\ &= a^2C_X(t_1, t_2) + b^2C_Y(t_1, t_2) \\ &= (a^2 + b^2)C_X(t_1, t_2) \\ &= (a^2 + b^2)C_X(t_1 - t_2) \end{aligned}$$

Thus, $Z(t)$ is also WSS.

(b) $Z(t) \sim \mathcal{N}(0, a^2 + b^2)$

Problem 6.70:

(a) $R_X(\tau) = e^{-2\alpha|\tau|}$ is continuous at $\tau = 0$. Thus, $X(t)$ is mean-square continuous at every t .

(b)

$$\begin{aligned} \frac{\partial}{\partial \tau} R_X(\tau) &= -2\alpha \text{sign}(\tau) e^{-2\alpha|\tau|} \\ \frac{\partial^2}{\partial^2 \tau} R_X(\tau) &= 4\alpha^2 e^{-2\alpha|\tau|} + 4\alpha \delta(\tau) \end{aligned}$$

The discontinuity in the sign function gives rise to the delta function. Thus, $X(t)$ is not mean-square differentiable.

(c) We assume the integral starts from 0:

$$Y(t) = \int_0^t X(\tau) d\tau$$

Consider the double integral:

$$\begin{aligned} R_Y(t_1, t_2) &= \int_0^{t_1} \int_0^{t_2} R_X(u, v) du dv \\ &= \int_0^{t_1} \int_0^{t_2} R_X(u - v) du dv \\ &= \int_0^{t_1} \int_0^{t_2} e^{-2\alpha|u-v|} du dv \\ &= \frac{\min(t_1, t_2)}{\alpha} (1 - e^{-2\alpha(t_1-t_2)}) + \frac{1}{4\alpha^2} (e^{-2\alpha t_1} + e^{-2\alpha t_2} - 1 - e^{-2\alpha(t_1-t_2)}) \end{aligned}$$

Since the above integral exists for $t_1 = t_2$, $X(t)$ is mean-square integrable. The mean of $Y(t)$ is zero and the covariance is given above.

Problem 6.71: $X(t)$ is WSS with autocorrelation function

$$R_X(\tau) = \sigma^2 e^{-\alpha\tau^2}$$

- (a) Since $R_X(\tau)$ is continuous at $\tau = 0$, $X(t)$ is mean-square continuous at every t .
- (b) Since $d^2R_X(\tau)/d\tau^2$ exists at $\tau = 0$, $X(t)$ is mean-square differentiable at every t . Let $X'(t) = dX(t)/dt$. Since $E[X(t)] = \text{constant}$,

$$E[X'(t)] = \frac{d}{dt}E[X(t)] = 0$$

Also,

$$R_{X'}(\tau) = -\frac{d^2}{d\tau^2}R_X(\tau) = 2\alpha\sigma^2e^{-\alpha\tau^2}(1 - 2\alpha\tau^2)$$

- (c) Since $X(t)$ is mean-square continuous, its mean-square integral exists. Consider

$$Y(t) = \int_0^t X(t') dt'$$

$$\begin{aligned} E[Y(t)] &= \int_0^t E[X(t)] dt \\ &= mt \end{aligned}$$

Assume $t_1 < t_2$:

$$\begin{aligned} R_Y(t_1, t_2) &= \int_0^{t_1} \int_0^{t_2} R_X(u - v) du dv \\ &= \sigma^2 \left[t_1 \int_{-t_1}^{t_2-t_1} e^{-\alpha\tau^2} d\tau + t_2 \int_{t_2-t_1}^{t_2} e^{-\alpha\tau^2} d\tau + \frac{1}{2\alpha} \left(-1 + e^{-\alpha t_1^2} + e^{-\alpha t_2^2} - e^{-\alpha(t_1-t_2)^2} \right) \right] \end{aligned}$$

If $t_1 \geq t_2$:

$$R_Y(t_1, t_2) = \sigma^2 \left[t_2 \int_{-t_2}^{t_1-t_2} e^{-\alpha\tau^2} d\tau + t_1 \int_{t_1-t_2}^{t_1} e^{-\alpha\tau^2} d\tau + \frac{1}{2\alpha} \left(-1 + e^{-\alpha t_1^2} + e^{-\alpha t_2^2} - e^{-\alpha(t_1-t_2)^2} \right) \right]$$

- (d) $X(t)$ is not necessarily Gaussian even though its autocorrelation function looks like a Gaussian pdf.

Problem 6.78: As discussed in class, $R_X(\tau) = 1$ and

$$\begin{aligned} \text{Var}[\langle X(t) \rangle_T] &= \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) C_X(\tau) d\tau \\ &= \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) d\tau \\ &= (1/2T)(1/2)(4T)(1) \\ &= 1. \end{aligned}$$

Thus $X(t)$ is not mean-ergodic.

Problem 6.79: Since $R_X(\tau) \rightarrow 0$ as $\tau \rightarrow \infty$, $X(t)$ is mean-ergodic.

Problem 6.80: $X(t) = A \cos(\omega t)$, where A has mean m and variance σ^2 .

(a)

$$\begin{aligned}\langle X(t) \rangle_T &= \frac{1}{2T} \int_{-T}^T X(t) dt \\ &= \frac{1}{2T} \int_{-T}^T A \cos(\omega t) dt \\ &= \frac{1}{2T} \frac{2A \sin(\omega T)}{\omega} \\ &= A \operatorname{sinc}(\omega T) \rightarrow 0 \text{ as } T \rightarrow \infty\end{aligned}$$

$E[X(t)] = E[A] \cos(\omega t) = m \cos(\omega t)$. Thus, $X(t)$ is mean-ergodic iff $m = E[A] = 0$.

(b)

$$\begin{aligned}R_X(t, t + \tau) &= E[A^2] \cos(\omega t) \cos(\omega(t + \tau)) \\ &= (\sigma^2 + m^2) \cos(\omega t) \cos(\omega(t + \tau)) \\ \langle X(t)X(t + \tau) \rangle_T &= \frac{1}{2T} \int_{-T}^T A^2 \cos(\omega t) \cos(\omega(t + \tau)) dt \\ &= \frac{1}{2T} \int_{-T}^T \frac{A^2}{2} [\cos(\omega \tau) + \cos(\omega(2t + \tau))] dt \\ &= \frac{1}{2T} \frac{A^2}{2} \cos(\omega \tau)(2T) + \frac{A^2}{2} \frac{\sin(\omega(2T + \tau)) - \sin(\omega(-2T + \tau))}{4\omega T} \\ &= \frac{A^2}{2} \cos(\omega \tau) \text{ as } T \rightarrow \infty\end{aligned}$$

Thus

$$\langle X(t)X(t + \tau) \rangle_T \not\rightarrow R_X(t, t + \tau)$$

Problem 6.81: $X(t) = A \cos(\omega t + \Theta)$, where A has mean m and variance σ^2 and Θ is uniform on $[0, 2\pi]$.

(a)

$$\begin{aligned}E[X(t)] &= E[A]E[\cos(\omega t + \Theta)] = m \cdot 0 = 0 = m_X \\ \langle X(t) \rangle_T &= \frac{1}{2T} \int_{-T}^T A \cos(\omega t + \Theta) dt \\ &= \frac{A \sin(\omega T + \Theta)}{\omega T} \\ &\rightarrow 0 = m_X\end{aligned}$$

(b)

$$\begin{aligned}E[X(t)X(t + \tau)] &= E[A^2]E[\cos(\omega t + \Theta) \cos(\omega(t + \tau) + \Theta)] \\ &= E[A^2]E[(1/2) \cos(\omega \tau) + (1/2) \cos(\omega(2t + \tau) + 2\Theta)] \\ &= \frac{(\sigma^2 + m^2) \cos(\omega \tau)}{2} = R_X(\tau) \\ \langle X(t)X(t + \tau) \rangle_T &= \frac{1}{2T} \int_{-T}^T A^2 \cos(\omega t + \Theta) \cos(\omega(t + \tau) + \Theta) dt \\ &= \frac{1}{2T} \int_{-T}^T A^2 [(1/2) \cos(\omega \tau) + (1/2) \cos(\omega(2t + \tau) + 2\Theta)] dt \\ &\rightarrow \frac{A^2 \cos(\omega \tau)}{2} \neq R_X(\tau)\end{aligned}$$